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### High Efficient and High Quality Surface Structuring of Metals

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### **Optimization Tasks**

### Efficiency

#### Maximize process efficiency Copper polished, 1064nm, Pav = 1W



#### use best suited pulse duration



#### **Strategy**

#### Optimize the structuring



### Use fast moving axes

**Throughput** 



#### synchronize axes with the laser

#### or parallel processes



### Specific Removal Rate of a Gaussian Beam

 Deduce specific removal rate by machining squares



### Specific Removal Rate of a Gaussian Beam

- Deduce specific removal rate by machining squares
- Theoretical Model [1]:

 $\frac{\dot{V}}{P_{av}} = \frac{1}{2} \cdot \frac{\delta}{\phi_{th}} \cdot \ln^2 \left( \frac{\phi_0}{\phi_{th}} \right)$ 

#### With:

 $\phi_{th}$ : Threshold fluence  $\delta$ : Energy penetration depth  $\phi_0$ : Peak fluence

- Optimum Point / Maximum rate  $\phi_{0,opt} = e^2 \cdot \phi_{th}$ ,  $\frac{\dot{V}_{max}}{P_{av}} = \frac{2}{e^2} \cdot \frac{\delta}{\phi_{th}}$
- Shorter Pulses -> Higher rates
- Process window defined by efficiency (copper, nickel, ?)



[1]: B. Neuenschwander et al, "From fs to sub-ns: Dependence of the Material Removal Rate on the Pulse Duration for Metals", Physics Procedia Vol. 41, pp. 787-794 (2013)



Squares machined with galvo:

- $f_r = 200 \text{ Hz}, w_0 = 16 \mu \text{m},$ pitch = 8  $\mu \text{m}$
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- Not exactly following model function
- Limited process window (also for other steel grades)

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### Synchronized marking

#### Unsynchronized



- jitter of the starting position of each line

# Synchronized



- well defined marking positions

Synchronized marking leads to highest precision [2]

[2]: Jaeggi B., Neuenschwander B. et al., "Ultra-high-precision surface structuring by synchronizing a galvo scanner with an ultra-short-pulsed laser system in MOPA arrangement," Proc. SPIE 8243, (2012)

### Synchronized marking







- Synchronized marking leads to highest precision
- Structuring information described in b/w-bitmap
- Definition of the start positions (upper left corner of bitmap)
- Clever distribution of the starting points
- Choose right pitch for best surface quality and roughness
- Best pitch is about half of a spot radius  $w_0$

[2]: Jaeggi B., Neuenschwander B. et al., "Ultra-high-precision surface structuring by synchronizing a galvo scanner with an ultra-short-pulsed laser system in MOPA arrangement," Proc. SPIE 8243, (2012)

### Examples with synchronized Galvo Scanner

#### Large area shark skin structure





#### Multi-pulse drilling on the fly





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### Marking Speed





- Working near the optimum point with a few 10W of average power demands:
  - High marking speeds of 100m/s and more (not accessible with galvo scanners).
  - Single pulse switching at repetition rates of a few MHz to about 20MHz.

### Polygon 1: Experimental set - up



#### Characteristics:

- Spot radius
  - Set up1:  $w_0 = 28.9 \ \mu m$
  - Set up2:  $w_0 = 22.6 \ \mu m$
- Circular polarization by using a λ/4waveplate
- Focal position on the sample surface

#### Laser System:

- ► Synchronized via SuperSync<sup>™</sup> technology
- FUEGO from Lumentum,  $\Delta \tau = 10$  ps, 50W, 1064nm,  $M^2 \le 1.2$
- Max 43 W on the workpiece

### Scale up to 43 W with 10ps pulses





- *f<sub>rep</sub>*: 4.1MHz
- ▶ *P<sub>m</sub>*: 25.6W
- ▶ Pitch: 14.5µm  $\rightarrow v_{scan}$ : 59.5m/s
- No. of Layers: 2233
- The process is scalable into the 50W regime with several MHz repetition rate

#### Is a further scale up above100W possible?

### Polygon 2: Set – up



- Amphos High Power Laser
  - $P_{av,max} = 350W$
  - $\Delta \tau = 500 \text{ fs} ... 5 \text{ ps}$  (used 3ps)
  - λ = 1030 nm
  - Linearly polarized

#### High speed Polygon

- Not synchronized
- 1 integrated galvo
- 12 facets
- ▶ f<sub>Obj</sub> = 100 mm
- $\sim v_{mark,max} = 480 \text{ m/s}$



- Maximum specific removal rate strongly depends on repetition rate
- Points to a "shielding" effect



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- Maximum specific removal rate strongly depends on repetition rate
- Points to a "shielding" effect
- Good surface quality up to maximum average power of 330W
  - Maximum removal rate 40mm<sup>3</sup>/min @ 5MHz
  - Small melting effects for 40MHz repetition rate



Repetition rate has only a small influence onto the maximum specific removal rate



- Repetition rate has only a small influence onto the maximum specific removal rate
- Smooth surface, good quality





- Repetition rate has only a small influence onto the maximum specific removal rate
- Bumpy surface at highest spec. removal rate for 10 MHz





- Repetition rate has only a small influence onto the maximum specific removal rate
- More pronounced at higher average power and repetition rate



### Steel: Heat accumulation

Finding of [3]:

- A part of the incoming energy is always converted to heat (38-40% for steel 1.4301)
- If ∆T<sub>max</sub> > 610 °C (just before the next pulse strikes on the surface) bumpy surface is supposed to appear



- Analytical expression: T(x, y, z, t)
- Pulsed beam along straight line



[3] F. Bauer et al., " Heat accumulation in ultra-short pulsed laser processing of metals", Opt. Expr., 23, 1035 - 1043 (2015)

### Temperature along a Scan Line



- Shown is the temperature along the scan line (x-axis) just before the next pulse strikes on the surface
- The previous pulse is located at x = 0

### **Steel: Temperature estimations**



Alternative strategies

Single Spot:

Multi Spot:

Enlarge the pitch:

Temporal, Bursts:

Increase spot size:



Spatial:

### Scale – up to $P_{av} = 100W$ : Enlarge pitch



- Pitch varied from 6 to 42 µm
- needed pitch  $\geq$  24 µm ( $\geq$  w<sub>0</sub>)
- v<sub>mark</sub> > 600 m/s

### "Interlaced" Mode

 A given spot pattern can also be machined



in n passes (pitch n times)





Squares machined with galvo scanner:

 $w_0 = 15.5 \ \mu m, \ p = 8 \ \mu m, \ 0.5 \ MHz$  $\phi_0 = 0.51 \ J/cm^2, \ 50 \ slices$ 



### Test of "Interlaced Mode" with Polygon Scanner

```
P_{av} = 42.8W, f = 8.2 MHz, \phi_o = 0.51 J/cm^2
```



 $v = 25 \text{ m/s}, p = 3.1 \mu\text{m}, 30 \text{ slices}$ 

0 μm EHT = 7.00 kV Signal A = SE2 Date :18 May 2015 BFH\_TI WD = 8.1 mm Mag = 4.00 K X Reference Mag = Out Dev. Josef Zürcher

 $v = 100 \text{ m/s}, p = 12.2 \mu\text{m}, 120 \text{ slices}$ 

- High pitch with interlaced mode works  $(\sqrt{)}$ 
  - Very high marking speeds ( > 600 m/s), synchronized (?)
  - High repetition rate (26 MHz) and single pulse switching (?)

### Scale – up to $P_{av} = 100W$ : Enlarge Spot Size



Spot radius w<sub>0</sub>: 22.6 µm - 50 µm

$$v_{mark} = 100 \text{ m/s} \sqrt{}$$

Result:

- w<sub>0</sub> ≥ 45 µm (√)
- ▶ f ≤ 6.6 MHz 🗸
- Will work with our polygon 1
  Limitations in precision and minimum structures size

### Conclusions

- Metals show an optimum fluence with maximum specific removal rate
- Process window (pulse energy) limited by efficiency and/or quality
- Synchronization is a key for precise machining
- Power scale up to 50W was demonstrated for copper and steel
- Further scale up can be limited
  - Heat accumulation (e.g. steel)
  - "shielding" effects (e.g. copper) ?
- Demonstrated up to 330W and 40mm<sup>3</sup>/min for copper
- For steel interlaced mode with high marking speeds, synchronization and single pulse switching or bigger spot sizes will be needed

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# Thank You for Your Attention