

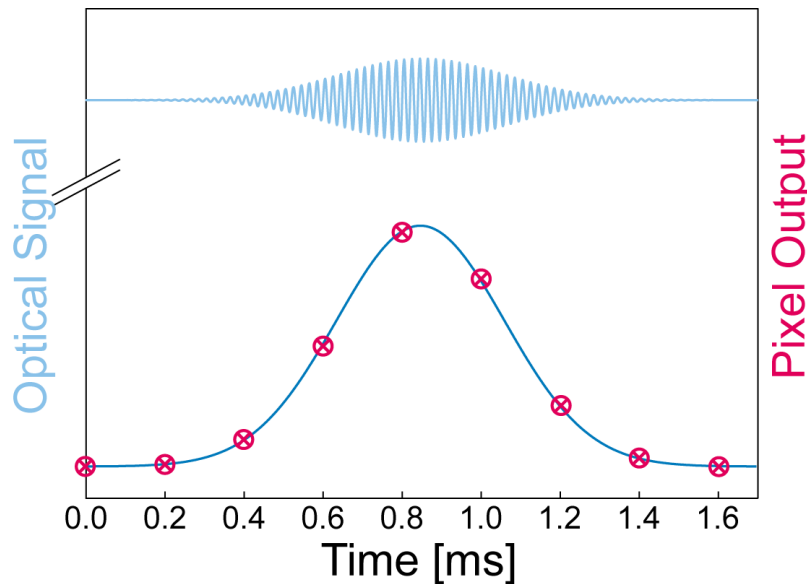
High-speed Lock-IN CMOS camera with pixel-level signal processing.



Motivation

- Single photodiode: $>1\text{GHz}$
 - Pixel array: 4096 pixel $\rightarrow \sim 100'000\text{ lines/s}$
 - 2D Camera: 1Mpixel $\rightarrow \sim 1000\text{ frames/s}$
- \rightarrow Data rate: $\sim 1\text{GB/s}$ \rightarrow complex to transfer and process in real time

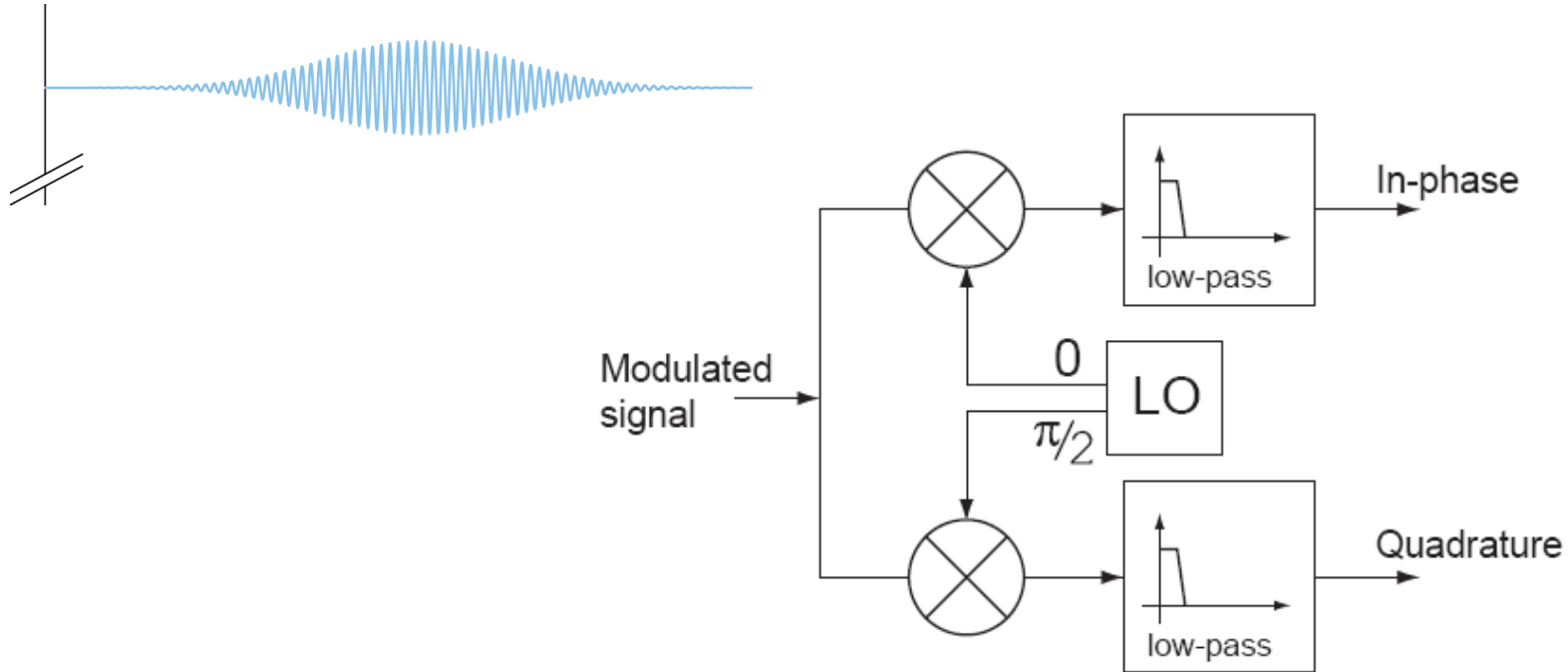
Modulated signal



- Used in many fields:
 - Amplitude:
 - white light interferometry
 - Spectroscopy (pump-probe)
 - Lock-IN detection
 - Phase:
 - interferometry
 - 3D fringe projection
 - Doppler measurements.

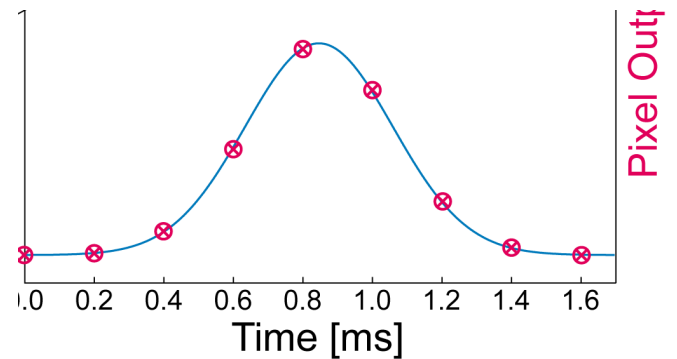
- Max frequency limited for 2D sensors

Lock-In function



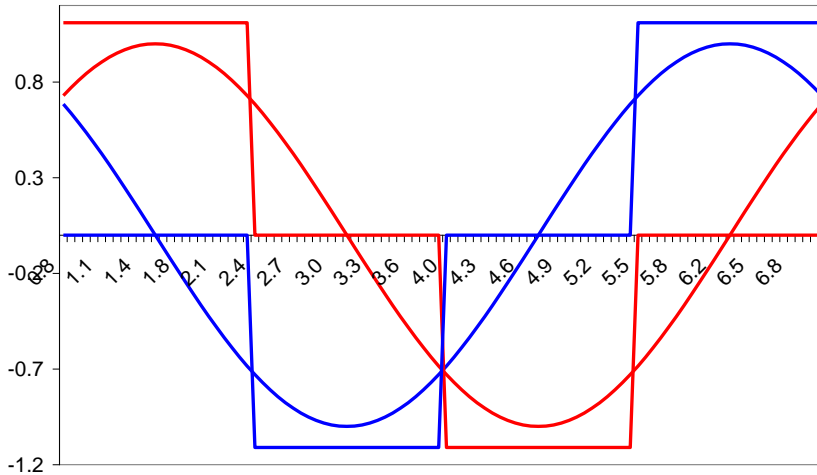
$$A_m \left[\Gamma \right] = \frac{\omega}{n_c \pi} \sqrt{I(T)^2 + Q(T)^2}$$

$$\varphi(T) = a \tan \left(\frac{Q(T)}{I(T)} \right)$$



In pixel implementation

S. Beer (CSEM)

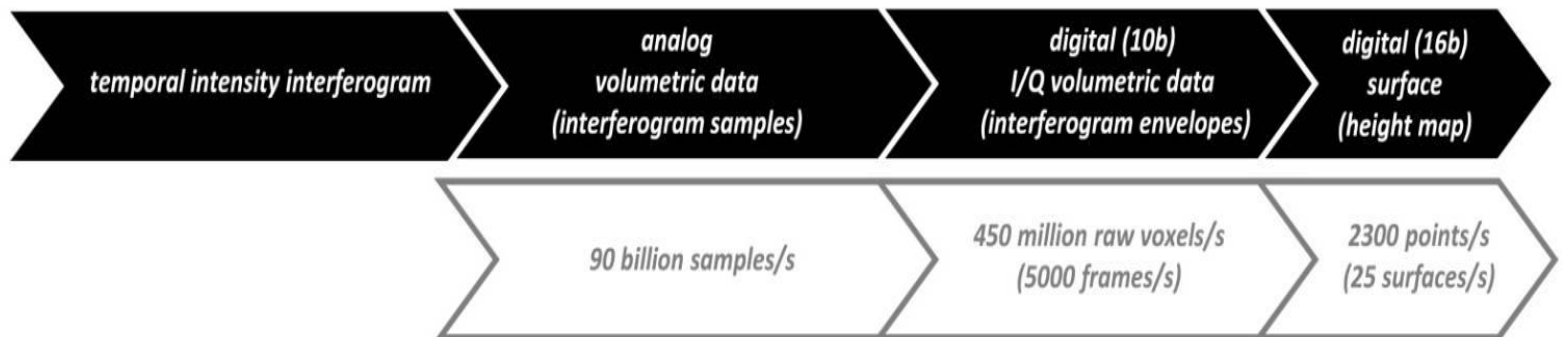
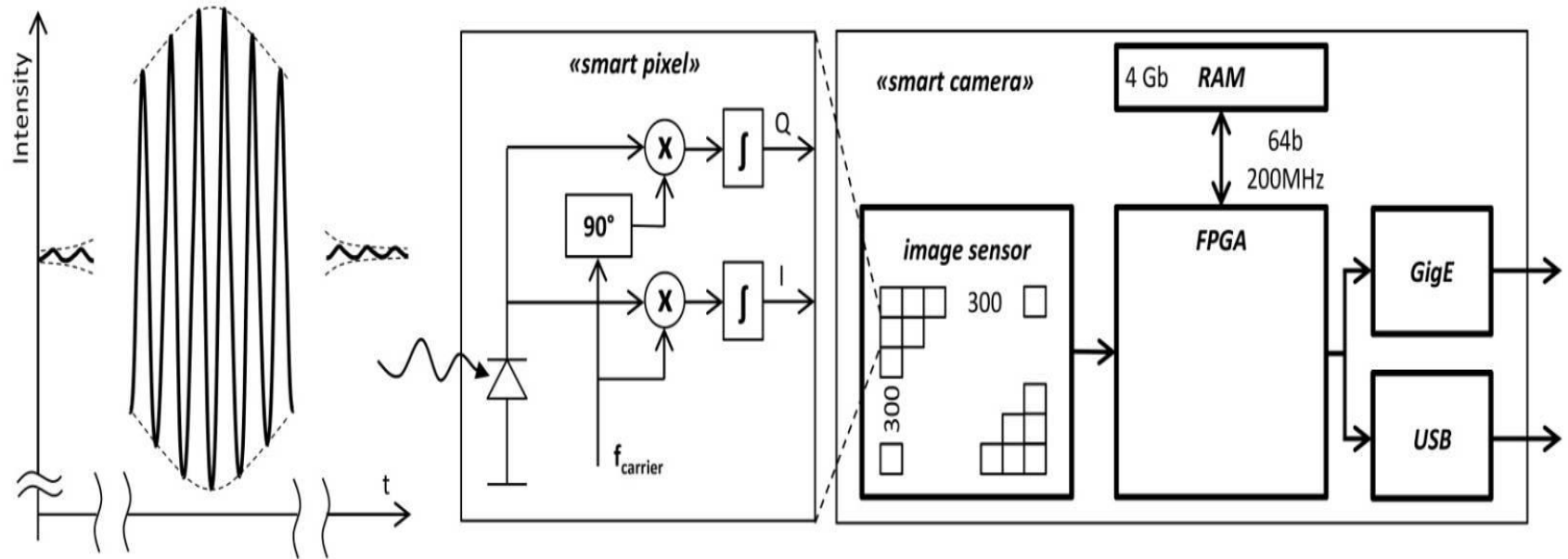


$$I\left(T + \frac{\pi}{4\omega}\right) \approx \sum_{i=nc}^{ncnF} \left(A_{4i} - A_{4i+2} \right)$$

$$Q\left(T + \frac{\pi}{4\omega}\right) \approx \sum_{i=nc}^{ncnF} \left(A_{4i+1} + A_{4i+3} \right)$$

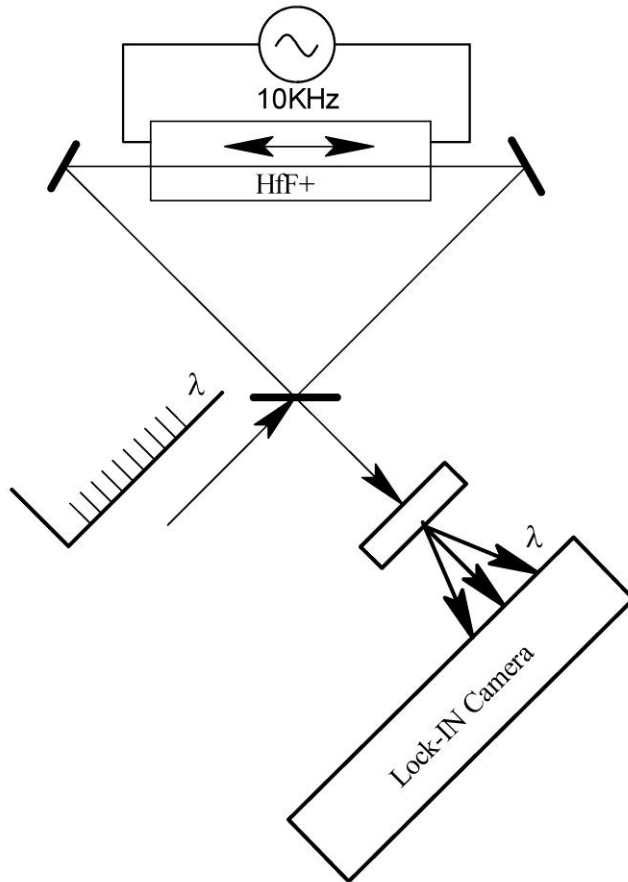
- Up to 1 Million analogue operations per second.
- Demodulation frequency: up to 250KHz.
- Up to 5000 I/Q frames per second for 300x300 pixel.
- Offset compensation circuit included in pixel.

Lock-IN camera



Frequency Comb Velocity-Modulation Spectroscopy.

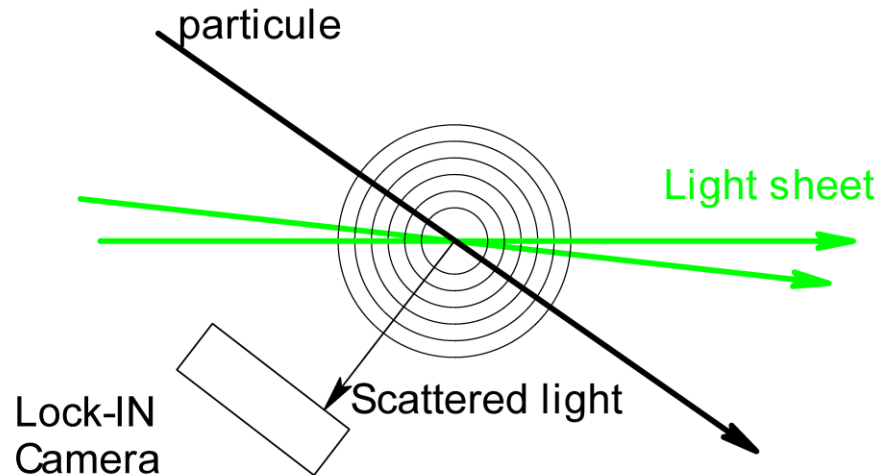
L.C. Sinclair et al, JILA: Phys. Rev. Lett. 107, 093002 (2011)



- 1500 simultaneous channels over 150 cm^{-1}
- 30 images acquired for a full range scan (in 30 min.)
- Fractional absorption sensitivity: 3×10^{-7} (30 times better than previous DC experiments)

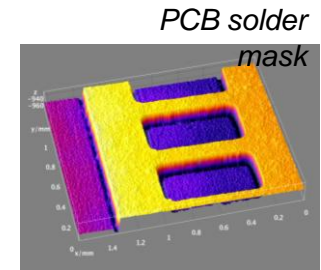
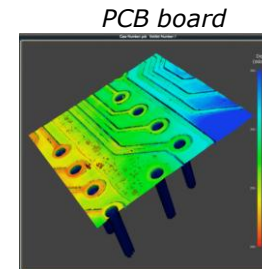
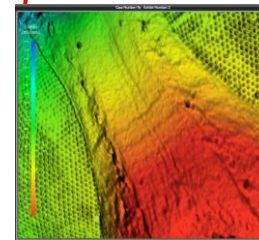
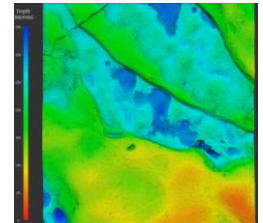
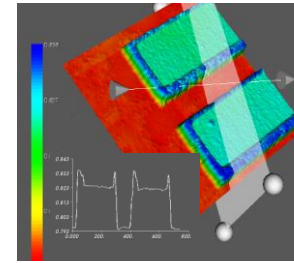
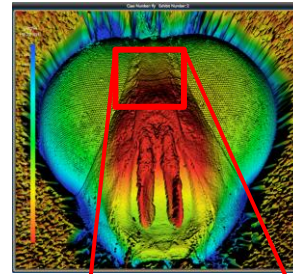
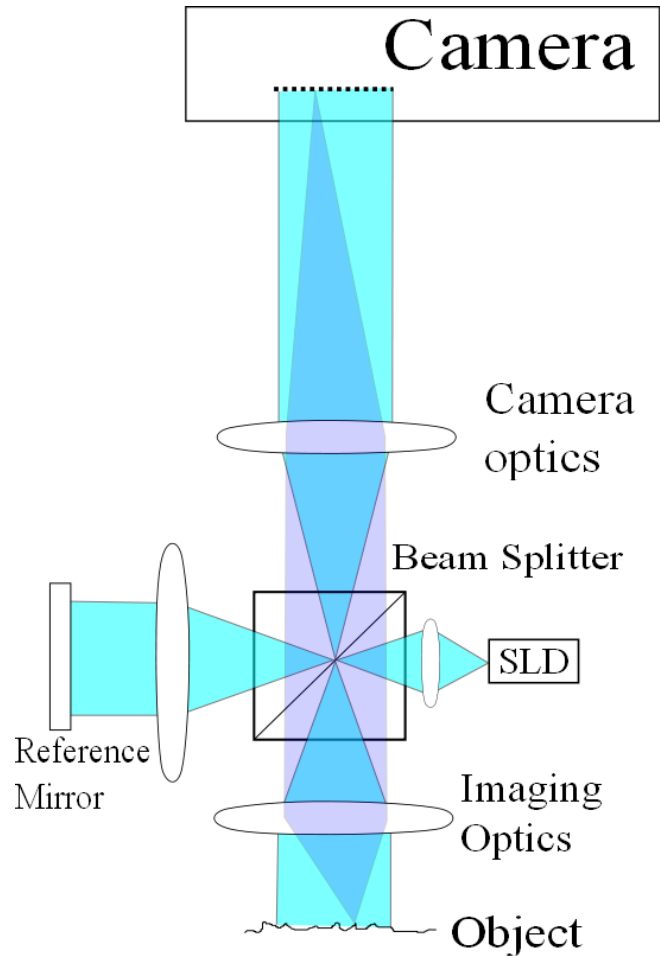
Imaging LASER Doppler velocimetry

A. Meier, T. Rösgen (ETHZ), 2010

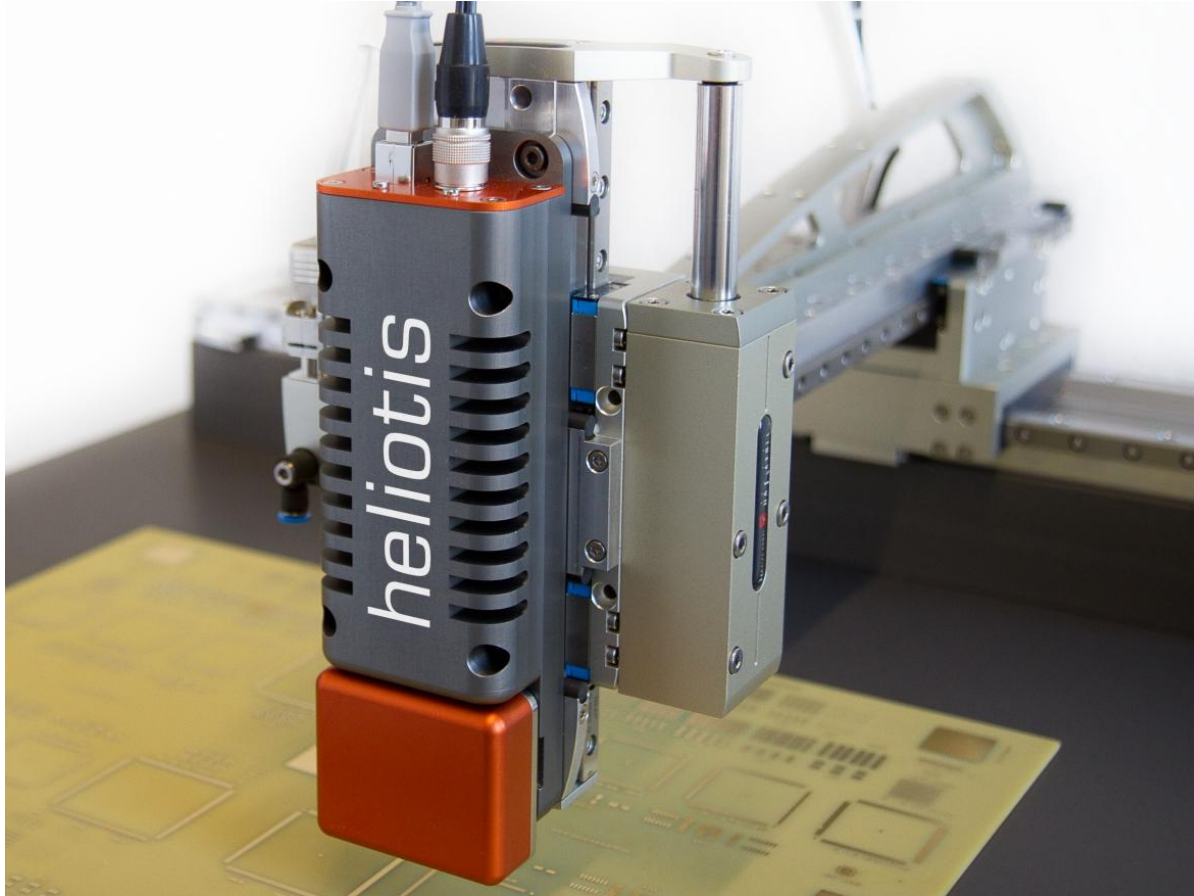


- Phase difference between frames allow to measure the frequency of scattered light.
- An image with velocity distribution can be acquired at once.
- Velocities up to 3m/s have been measured.
- With higher power laser, up to 40m/s is feasible.

White light interferometry



3D Vision Module H3



Applications

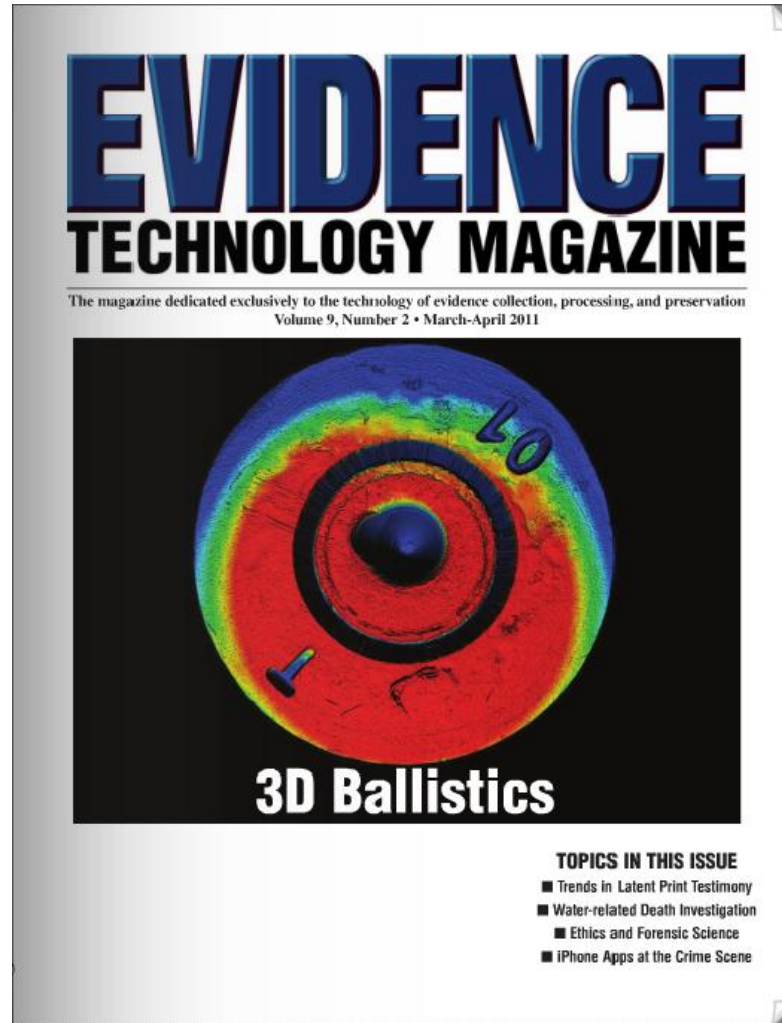
- > in-line quality inspection
- > lab automation
- > surface roughness
- > geometrical feature control
- > OEM integration
- > statistical process control

Features

- > surface topography
- > volume tomography
- > robust and fast
- > sub-um resolution
- > measures any surface
- > small form factor
- > software modules for rapid integration (Windows, Mac, Linux)
- > modular system of linear motors (portal robot)

Ballistics application

Pyramidal Technologies



Parallel confocal 3D Imaging

3d-Intraoral Scanner



Traditional

Digital

Total:

- 28 Steps
- 2 Traditional impression
- 2 Gypsum Model (+ analog)
- 2 Shipping /Back

- 14 Steps
- 1 Digital impression
- 1 Milling model & stumps
- 1 Shipping/Back

5 working hours

-60% less working time